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# GALAHAD

# BSC

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USER DOCUMENTATION

GALAHAD Optimization Library version 2.6

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## 1 SUMMARY

Given matrices **A** and diagonal **D**, this package forms the **Schur complement**  $\mathbf{S} = \mathbf{A}\mathbf{D}\mathbf{A}^T$  in sparse format. Full advantage is taken of any zero coefficients in the matrices **A**.

**ATTRIBUTES — Versions:** GALAHAD\_BSC\_single, GALAHAD\_BSC\_double. **Uses:** GALAHAD\_CLOCK, GALAHAD\_SYMBOLS, GALAHAD\_SPACE, GALAHAD\_SMT, GALAHAD\_QPT, GALAHAD\_SPECFILE, **Date:** October 2013. **Origin:** N. I. M. Gould, Rutherford Appleton Laboratory. **Language:** Fortran 95 + TR 15581 or Fortran 2003.

## 2 HOW TO USE THE PACKAGE

Access to the package requires a USE statement such as

*Single precision version*

```
USE GALAHAD_BSC_single
```

*Double precision version*

```
USE GALAHAD_BSC_double
```

If it is required to use both modules at the same time, the derived types SMT\_type, QPT\_problem\_type, BSC\_time\_type, BSC\_control\_type, BSC\_inform\_type and BSC\_data\_type (§2.2) and the subroutines BSC\_initialize, BSC\_form, BSC\_terminate, (§2.3) and BSC\_read\_specfile (§2.5) must be renamed on one of the USE statements.

### 2.1 Matrix storage formats

The input matrix **A** may be stored in a variety of input formats.

#### 2.1.1 Dense storage format

The matrix **A** is stored as a compact dense matrix by rows, that is, the values of the entries of each row in turn are stored in order within an appropriate real one-dimensional array. Component  $n*(i-1) + j$  of the storage array A%val will hold the value  $a_{ij}$  for  $i = 1, \dots, m$ ,  $j = 1, \dots, n$ .

#### 2.1.2 Sparse co-ordinate storage format

Only the nonzero entries of the matrices are stored. For the  $l$ -th entry of **A**, its row index  $i$ , column index  $j$  and value  $a_{ij}$  are stored in the  $l$ -th components of the integer arrays A%row, A%col and real array A%val, respectively. The order is unimportant, but the total number of entries A%ne is also required.

#### 2.1.3 Sparse row-wise storage format

Again only the nonzero entries are stored, but this time they are ordered so that those in row  $i$  appear directly before those in row  $i+1$ . For the  $i$ -th row of **A**, the  $i$ -th component of an integer array A%ptr holds the position of the first entry in this row, while A%ptr( $m+1$ ) holds the total number of entries plus one. The column indices  $j$  and values  $a_{ij}$

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of the entries in the  $i$ -th row are stored in components  $l = A\%ptr(i), \dots, A\%ptr(i+1) - 1$  of the integer array  $A\%col$ , and real array  $A\%val$ , respectively.

For sparse matrices, this scheme almost always requires less storage than its predecessor.

## 2.2 The derived data types

Four derived data types are accessible from the package.

### 2.2.1 The derived data type for holding matrices

The derived data type `SMT_TYPE` is used to hold the matrix **A**. The components of `SMT_TYPE` used here are:

`type` is a rank-one allocatable array of type default `CHARACTER`, that is used to indicate the storage scheme used. If the dense storage scheme (see §2.1.1), is used, the first five components of `type` must contain the string `DENSE`. For the sparse co-ordinate scheme (see §2.1.2), the first ten components of `type` must contain the string `COORDINATE`, and for the sparse row-wise storage scheme (see §2.1.3), the first fourteen components of `type` must contain the string `SPARSE_BY_ROWS`.

For convenience, the procedure `SMT_put` may be used to allocate sufficient space and insert the required keyword into `type`. For example, if **A** is of derived type `SMT_type` and we wish to use the co-ordinate storage scheme, we may simply

```
CALL SMT_put( A%type, 'COORDINATE', istat )
```

See the documentation for the GALAHAD package `SMT` for further details on the use of `SMT_put`.

`ne` is a scalar variable of type default `INTEGER`, that holds the number of matrix entries.

`val` is a rank-one allocatable array of type default `REAL` (double precision in `GALAHAD_BSC_double`) and dimension at least `ne`, that holds the values of the entries. Any duplicated entries that appear in the sparse co-ordinate or row-wise schemes will be summed.

`row` is a rank-one allocatable array of type default `INTEGER`, and dimension at least `ne`, that may hold the row indices of the entries. (see §2.1.2).

`col` is a rank-one allocatable array of type default `INTEGER`, and dimension at least `ne`, that may hold the column indices of the entries (see §2.1.2–2.1.3).

`ptr` is a rank-one allocatable array of type default `INTEGER`, and dimension at least `m + 1`, that may hold the pointers to the first entry in each row (see §2.1.3).

### 2.2.2 The derived data type for holding control parameters

The derived data type `BSC_control_type` is used to hold controlling data. Default values may be obtained by calling `BSC_initialize` (see §2.3.1), while components may also be changed by calling `GALAHAD_BSC_read_spec` (see §2.5.1). The components of `BSC_control_type` are:

`error` is a scalar variable of type default `INTEGER`, that holds the stream number for error messages. Printing of error messages in `BSC_solve` and `BSC_terminate` is suppressed if `error`  $\leq 0$ . The default is `error` = 6.

`out` is a scalar variable of type default `INTEGER`, that holds the stream number for informational messages. Printing of informational messages in `BSC_solve` is suppressed if `out`  $< 0$ . The default is `out` = 6.

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`print_level` is a scalar variable of type default `INTEGER`, that is used to control the amount of informational output which is required. No informational output will occur if `print_level ≤ 0`. If `print_level = 1`, a single line of output will be produced for each iteration of the process. If `print_level ≥ 2`, this output will be increased to provide significant detail of each iteration. The default is `print_level = 0`.

`new_a` is a scalar variable of type default `INTEGER`, that is used to indicate how **A** has changed (if at all) since the previous call to `BSC_form_and_factorize`. Possible values are:

- 0 **A** is unchanged
- 1 the values in **A** have changed, but its nonzero structure is as before.
- 2 both the values and structure of **A** have changed.

The default is `new_a = 2`.

`max_col` is a scalar variable of type default `INTEGER`, that specifies the maximum number of nonzeros in a column of **A** which is permitted when building the Schur-complement. Any negative value will be interpreted as `m`. The default is `max_col = -1`.

`space_critical` is a scalar variable of type default `LOGICAL`, that must be set `.TRUE.` if space is critical when allocating arrays and `.FALSE.` otherwise. The package may run faster if `space_critical` is `.FALSE.` but at the possible expense of a larger storage requirement. The default is `space_critical = .FALSE..`

`deallocate_error_fatal` is a scalar variable of type default `LOGICAL`, that must be set `.TRUE.` if the user wishes to terminate execution if a deallocation fails, and `.FALSE.` if an attempt to continue will be made. The default is `deallocate_error_fatal = .FALSE..`

`prefix` is a scalar variable of type default `CHARACTER` and length 30, that may be used to provide a user-selected character string to preface every line of printed output. Specifically, each line of output will be prefaced by the string `prefix(2:LEN(TRIM(prefix))-1)`, thus ignoring the first and last non-null components of the supplied string. If the user does not want to preface lines by such a string, they may use the default `prefix = ""`.

### 2.2.3 The derived data type for holding informational parameters

The derived data type `BSC_inform_type` is used to hold parameters that give information about the progress and needs of the algorithm. The components of `BSC_inform_type` are:

`status` is a scalar variable of type default `INTEGER`, that gives the exit status of the algorithm. See §2.4 for details.

`alloc_status` is a scalar variable of type default `INTEGER`, that gives the status of the last attempted array allocation or deallocation. This will be 0 if `status = 0`.

`bad_alloc` is a scalar variable of type default `CHARACTER` and length 80, that gives the name of the last internal array for which there were allocation or deallocation errors. This will be the null string if `status = 0`.

`max_col_a` is a scalar variable of type default `INTEGER`, that gives the maximum number of entries in a column of **A**.

`exceeds_max_col` is a scalar variable of type default `INTEGER`, that gives the number of columns of **A** that have more entries than the limit specified by `control%max_col`.

`time` is a scalar variable of type default `REAL` (double precision in `GALAHAD_BSC_double`), that gives the total CPU time (in seconds) spent in the package.

`clock_time` is a scalar variable of type default `REAL` (double precision in `GALAHAD_BSC_double`), that gives the total elapsed system clock time (in seconds) spent in the package.

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### 2.2.4 The derived data type for holding problem data

The derived data type `BSC_data_type` is used to hold all the data for the problem and the workspace arrays used to construct the Schur complement between calls of BSC procedures. This data should be preserved, untouched, from the initial call to `BSC_initialize` to the final call to `BSC_terminate`.

### 2.3 Argument lists and calling sequences

There are three procedures for user calls (see §2.5 for further features):

1. The subroutine `BSC_initialize` is used to set default values, and initialize private data, before solving one or more problems with the same sparsity and bound structure.
2. The subroutine `BSC_form` is called to form the Schur complement.
3. The subroutine `BSC_terminate` is provided to allow the user to automatically deallocate array components of the private data, allocated by `BSC_form_and_factorize` at the end of the solution process.

We use square brackets [ ] to indicate OPTIONAL arguments.

#### 2.3.1 The initialization subroutine

Default values are provided as follows:

```
CALL BSC_initialize( data, control, inform )
```

`data` is a scalar `INTENT(INOUT)` argument of type `BSC_data_type` (see §2.2.4). It is used to hold data about the problem being solved.

`control` is a scalar `INTENT(OUT)` argument of type `BSC_control_type` (see §2.2.2). On exit, `control` contains default values for the components as described in §2.2.2. These values should only be changed after calling `BSC_initialize`.

`inform` is a scalar `INTENT(OUT)` argument of type `BSC_inform_type` (see Section 2.2.3). A successful call to `BSC_initialize` is indicated when the component `status` has the value 0. For other return values of `status`, see Section 2.4.

#### 2.3.2 The subroutine for forming the Schur complement

The sparse matrix  $S = ADA^T$  is formed as follows:

```
CALL BSC_form_and_factorize( m, n, A, S, data, control, inform[, D] )
```

`m` is a scalar `INTENT(IN)` argument of type default `INTEGER` that specifies the number of rows of **A**. **Restriction:**  $m \geq 0$ .

`n` is a scalar `INTENT(IN)` argument of type default `INTEGER` that specifies the number of columns of **A**. **Restriction:**  $n > 0$ .

`A` is a scalar `INTENT(IN)` argument of type `SMT_type` whose components must be set to specify the data defining the matrix **A** (see §2.2.1).

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`S` is a scalar `INTENT(OUT)` argument of type `SMT_type` whose components will be set to specify the *lower triangle* of the Schur complement  $S = ADA^T$ . In particular, the nonzeros of the lower triangle of  $S$  will be returned in coordinate form (see §2.1.2). Specifically `S%type` contains the string `tt COORDINATE`, `S%ne` gives the number of nonzeros and the array entries `S%row(i)`, `S%col(i)` and `S%val(i)`,  $i = 1, \dots, S\%ne$  give row and column indices and values of the entries in the lower triangle of  $S$  (see §2.2.1). In addition, for compatibility with other GALAHAD packages, `S%m` and `S%n` provide the row and column dimensions,  $m$ , of  $S$ .

`data` is a scalar `INTENT(INOUT)` argument of type `BSC_data_type` (see §2.2.4). It is used to hold data about the problem being solved. It must not have been altered **by the user** since the last call to `BSC_initialize`.

`control` is a scalar `INTENT(IN)` argument of type `BSC_control_type` (see §2.2.2). Default values may be assigned by calling `BSC_initialize` prior to the first call to `BSC_solve`.

`inform` is a scalar `INTENT(OUT)` argument of type `BSC_inform_type` (see §2.2.3). A successful call to `BSC_solve` is indicated when the component `status` has the value 0. For other return values of `status`, see §2.4.

`D` is a rank-one `OPTIONAL INTENT(IN)` argument of type `REAL` (double precision in `GALAHAD_BSC_double`) and length at least `n`, whose  $i$ -th component give the value of the  $i$ -th diagonal entry of the matrix  $D$ . If `D` is absent,  $D$  will be assumed to be the identity matrix.

### 2.3.3 The termination subroutine

All previously allocated arrays are deallocated as follows:

```
CALL BSC_terminate( data, control, inform )
```

`data` is a scalar `INTENT(INOUT)` argument of type `BSC_data_type` exactly as for `BSC_solve`, which must not have been altered **by the user** since the last call to `BSC_initialize`. On exit, array components will have been deallocated.

`control` is a scalar `INTENT(IN)` argument of type `BSC_control_type` exactly as for `BSC_solve`.

`inform` is a scalar `INTENT(OUT)` argument of type `BSC_inform_type` exactly as for `BSC_solve`. Only the component `status` will be set on exit, and a successful call to `BSC_terminate` is indicated when this component `status` has the value 0. For other return values of `status`, see §2.4.

## 2.4 Warning and error messages

A negative value of `inform%status` on exit from `BSC_form_and_factorize`, `BSC_solve` or `BSC_terminate` indicates that an error has occurred. No further calls should be made until the error has been corrected. Possible values are:

- 1. An allocation error occurred. A message indicating the offending array is written on unit `control%error`, and the returned allocation status and a string containing the name of the offending array are held in `inform%alloc_status` and `inform%bad_alloc` respectively.
- 2. A deallocation error occurred. A message indicating the offending array is written on unit `control%error` and the returned allocation status and a string containing the name of the offending array are held in `inform%alloc_status` and `inform%bad_alloc` respectively.
- 3. One of the restrictions  $n > 0$  or  $m \geq 0$  or requirements that `prob%A_type` contain the string 'DENSE', 'COORDINATE' or 'SPARSE\_BY\_ROWS' has been violated.
- 46 A row of  $A$  has more than `control%max_col` entries.

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## 2.5 Further features

In this section, we describe an alternative means of setting control parameters, that is components of the variable control of type `BSC_control_type` (see §2.2.2), by reading an appropriate data specification file using the subroutine `BSC_read_specfile`. This facility is useful as it allows a user to change BSC control parameters without editing and recompiling programs that call BSC.

A specification file, or specfile, is a data file containing a number of "specification commands". Each command occurs on a separate line, and comprises a "keyword", which is a string (in a close-to-natural language) used to identify a control parameter, and an (optional) "value", which defines the value to be assigned to the given control parameter. All keywords and values are case insensitive, keywords may be preceded by one or more blanks but values must not contain blanks, and each value must be separated from its keyword by at least one blank. Values must not contain more than 30 characters, and each line of the specfile is limited to 80 characters, including the blanks separating keyword and value.

The portion of the specification file used by `BSC_read_specfile` must start with a "BEGIN BSC" command and end with an "END" command. The syntax of the specfile is thus defined as follows:

```
( .. lines ignored by BSC_read_specfile .. )
BEGIN BSC
    keyword      value
    .....      .....
    keyword      value
END
( .. lines ignored by BSC_read_specfile .. )
```

where keyword and value are two strings separated by (at least) one blank. The "BEGIN BSC" and "END" delimiter command lines may contain additional (trailing) strings so long as such strings are separated by one or more blanks, so that lines such as

```
BEGIN BSC SPECIFICATION
```

and

```
END BSC SPECIFICATION
```

are acceptable. Furthermore, between the "BEGIN BSC" and "END" delimiters, specification commands may occur in any order. Blank lines and lines whose first non-blank character is ! or \* are ignored. The content of a line after a ! or \* character is also ignored (as is the ! or \* character itself). This provides an easy manner to "comment out" some specification commands, or to comment specific values of certain control parameters.

The value of a control parameters may be of three different types, namely integer, logical or real. Integer and real values may be expressed in any relevant Fortran integer and floating-point formats (respectively). Permitted values for logical parameters are "ON", "TRUE", ".TRUE.", "T", "YES", "Y", or "OFF", "NO", "N", "FALSE", ".FALSE." and "F". Empty values are also allowed for logical control parameters, and are interpreted as "TRUE".

The specification file must be open for input when `BSC_read_specfile` is called, and the associated device number passed to the routine in device (see below). Note that the corresponding file is REWINDed, which makes it possible to combine the specifications for more than one program/routine. For the same reason, the file is not closed by `BSC_read_specfile`.

### 2.5.1 To read control parameters from a specification file

Control parameters may be read from a file as follows:

```
CALL BSC_read_specfile( control, device )
```

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`control` is a scalar `INTENT(INOUT)` argument of type `BSC_control_type` (see §2.2.2). Default values should have already been set, perhaps by calling `BSC_initialize`. On exit, individual components of `control` may have been changed according to the commands found in the specfile. Specfile commands and the component (see §2.2.2) of `control` that each affects are given in Table 2.1.

command	component of control	value type
error-printout-device	%error	integer
printout-device	%out	integer
print-level	%print_level	integer
has-a-changed	%new_a	integer
maximum-column-nonzeros-in-schur-complement	%max_col	integer
space-critical	%space_critical	logical
deallocate-error-fatal	%deallocate_error_fatal	logical
output-line-prefix	%prefix	character

Table 2.1: Specfile commands and associated components of `control`.

`device` is a scalar `INTENT(IN)` argument of type `default_INTEGER`, that must be set to the unit number on which the specfile has been opened. If `device` is not open, `control` will not be altered and execution will continue, but an error message will be printed on unit `control%error`.

## 2.6 Information printed

If `control%print_level` is positive, information about the progress of the algorithm will be printed on unit `control%out`. If `control%print_level`  $\geq 1$ , statistics concerning the formation of **S** as well as warning and error messages will be reported.

## 3 GENERAL INFORMATION

**Use of common:** None.

**Workspace:** Provided automatically by the module.

**Other routines called directly:** None.

**Other modules used directly:** `BSC_solve` calls the GALAHAD packages `GALAHAD_CLOCK`, `GALAHAD_SYMBOLS`, `GALAHAD_SPACE`, `GALAHAD_SMT`, `GALAHAD_QPT` and `GALAHAD_SPECFILE`,

**Input/output:** Output is under control of the arguments `control%error`, `control%out` and `control%print_level`.

**Restrictions:**  $n > 0$ ,  $m \geq 0$ , `A_type`  $\in \{ \text{'DENSE'}, \text{'COORDINATE'}, \text{'SPARSE-BY-ROWS'} \}$ .

**Portability:** ISO Fortran 95 + TR 15581 or Fortran 2003. The package is thread-safe.

## 4 EXAMPLE OF USE

Suppose we form the Schur complement  $\mathbf{S} = \mathbf{A}\mathbf{D}\mathbf{A}^T$  with matrix data

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & & \\ & & 1 & 1 \\ 1 & & & 1 \end{pmatrix} \text{ and } \mathbf{D} = \begin{pmatrix} 1 & & & \\ & 2 & & \\ & & 3 & \\ & & & 4 \end{pmatrix}$$

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Then storing the matrices in sparse co-ordinate format, we may use the following code:

```
! THIS VERSION: GALAHAD 2.6 - 21/10/2013 AT 13:00 GMT.
PROGRAM GALAHAD_BSC_EXAMPLE
USE GALAHAD_BSC_double      ! double precision version
IMPLICIT NONE
INTEGER, PARAMETER :: wp = KIND( 1.0D+0 ) ! set precision
TYPE ( BSC_data_type ) :: data
TYPE ( BSC_control_type ) :: control
TYPE ( BSC_inform_type ) :: inform
INTEGER, PARAMETER :: m = 3, n = 4, a_ne = 6
TYPE ( SMT_type ) :: A, S
REAL ( KIND = wp ), DIMENSION( n ) :: D
INTEGER :: i
D( 1 : n ) = (/ 1.0_wp, 2.0_wp, 3.0_wp, 4.0_wp /)
! sparse co-ordinate storage format
CALL SMT_put( A%type, 'COORDINATE', i )      ! storage for A
ALLOCATE( A%val( a_ne ), A%row( a_ne ), A%col( a_ne ) )
A%ne = a_ne
A%val = (/ 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp /) ! Jacobian A
A%row = (/ 1, 1, 2, 2, 3, 3 /)
A%col = (/ 1, 2, 3, 4, 1, 4 /)
! problem data complete
CALL BSC_initialize( data, control, inform ) ! Initialize control parameters
CALL BSC_form( m, n, A, S, data, control, inform, D = D ) ! Form S
IF ( inform%status == 0 ) THEN                ! Successful return
  WRITE( 6, "( ' S:', /, ( ' row ', I2, ', column ', I2,
    & ', value = ', F4.1 ) )" )                &
  ( S%row( i ), S%col( i ), S%val( i ), i = 1, S%ne )
ELSE                                           ! Error returns
  WRITE( 6, "( ' BSC_solve exit status = ', I6 ) " ) inform%status
END IF
CALL BSC_terminate( data, control, inform ) ! delete internal workspace
END PROGRAM GALAHAD_BSC_EXAMPLE
```

This produces the following output:

```
S:
row 1, column 1, value = 3.0
row 3, column 1, value = 1.0
row 2, column 2, value = 7.0
row 3, column 2, value = 4.0
row 3, column 3, value = 5.0
```

The same problem may be solved holding the data in a sparse row-wise storage format by replacing the lines

```
! sparse co-ordinate storage format
...
! problem data complete
```

by

```
! sparse row-wise storage format
CALL SMT_put( A%type, 'SPARSE_BY_ROWS', i ) ! storage for A
ALLOCATE( A%val( a_ne ), A%col( a_ne ), A%ptr( m + 1 ) )
A%val = (/ 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp, 1.0_wp /) ! matrix A
A%col = (/ 1, 2, 3, 4, 1, 4 /)
A%ptr = (/ 1, 3, 5, 7 /)                ! Set row pointers
! problem data complete
```

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or using a dense storage format with the replacement lines

```
! dense storage format
  CALL SMT_put( A%type, 'DENSE', i ) ! storage for A
  ALLOCATE( A%val( n * m ) )
  A%val = (/ 1.0_wp, 1.0_wp, 0.0_wp, 0.0_wp, 0.0_wp, 0.0_wp,      &
            1.0_wp, 1.0_wp, 1.0_wp, 0.0_wp, 0.0_wp, 1.0_wp /) ! A
! problem data complete
```

respectively.